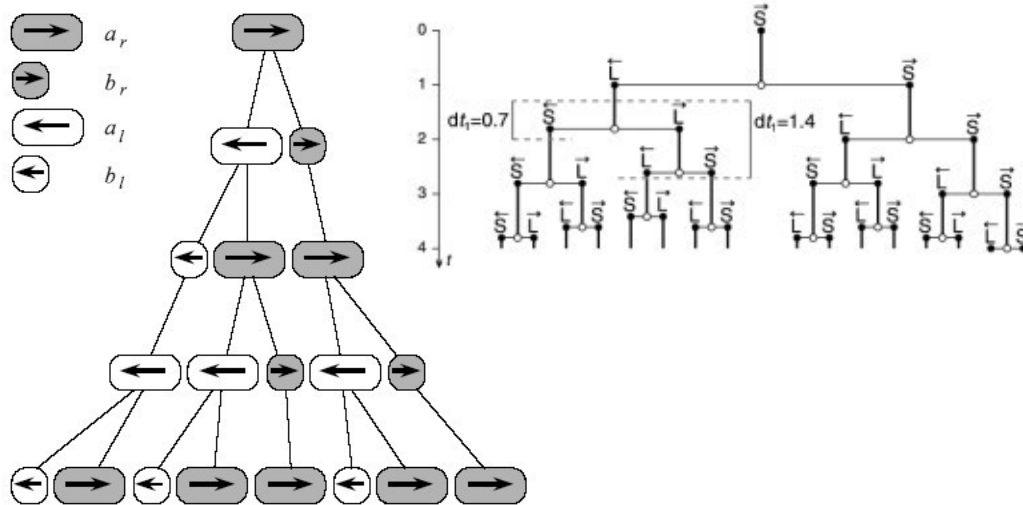


# L-Systems

# L-Systems: A Language for Modeling Growth

- Aristid Lindenmayer (1925-1989)
  - *Anabaena catenula*
  - 1968 – formalism for simulating the development of multicellular organisms
  - Lindenmayer systems (L-systems) – parallel string rewriting systems



Development of a filament (*Anabaena catenula*)



# L-Systems: A Language for Modeling Growth

- Subsequently applied to investigate higher plants and plant organs
- L-systems conceived as mathematical theory of plant development
- Przemyslaw Prusinkiewicz
  - extended L-systems in various ways



# D0L-Systems

- Deterministic context-free L-systems
  - Defined by a formal grammar  $G = \langle V, \omega, P \rangle$ 
    - $V$  is the alphabet of the system
    - $\omega \in V^+$  is a nonempty word called the axiom
    - $P \subset V \times V^*$  is a finite set of productions
- $V^+$  is the set of all nonempty words over  $V$
- $V^*$  is the set of all words over  $V$
- if no production is specified for a given letter, the identity production  $a \rightarrow a$  is assumed

# D0L-Systems

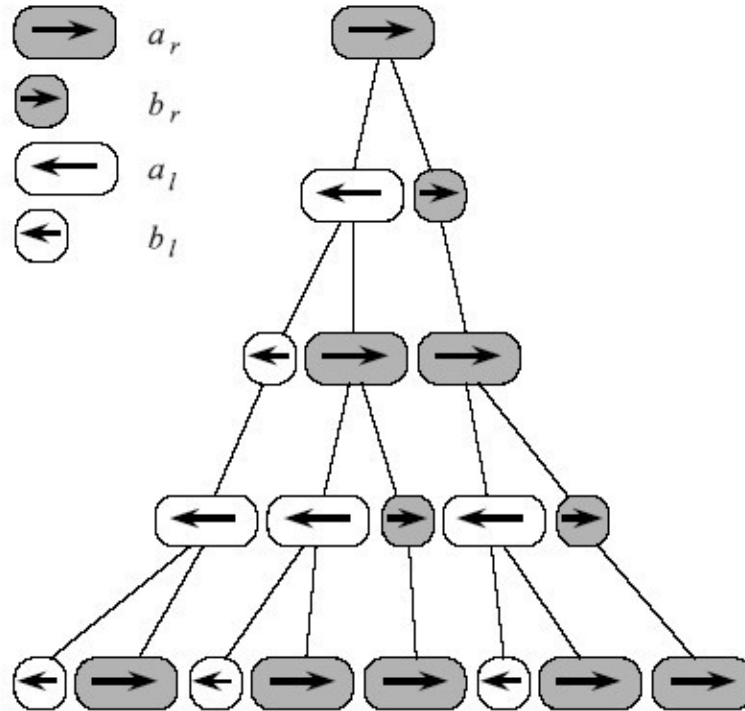
$$\omega : a_r$$

$$p_1 : a_r \rightarrow a_l b_r$$

$$p_2 : a_l \rightarrow b_l a_r$$

$$p_3 : b_r \rightarrow a_r$$

$$p_4 : b_l \rightarrow a_l$$



$a_r$

$a_l b_r$

$b_l a_r a_r$

$a_l a_l b_r a_l b_r$

$b_l a_r b_l a_r a_r b_l a_r a_r$

Development of a filament (*Anabaena catenula*)

# Turtle Graphics

- Geometric interpretation of L-systems
  - F** move forward by a fixed step of length  $d$  and draw a line from the old to the new position
  - f** move forward (as **F**) but do not draw the line
  - +** turn left (counterclockwise) by a fixed angle  $\delta$
  - turn right (clockwise) by the angle  $\delta$

Using trigonometry the following table can be deduced:

| command  | the state of the turtle $(x, y, a)$ is changed to: |
|----------|--|
| <b>F</b> | $(x+d\cos a, y+d\sin a, a)$                        |
| <b>f</b> | $(x+d\cos a, y+d\sin a, a)$                        |
| <b>+</b> | $(x, y, a-\delta)$                                 |
| <b>-</b> | $(x, y, a+\delta)$                                 |

$x, y$  define position on the plane, angle  $a$  orientation

# Growing Classical Fractals with L-Systems

- Koch curve

L-system:

Axiom:

Production rules:

Parameter:

Koch curve

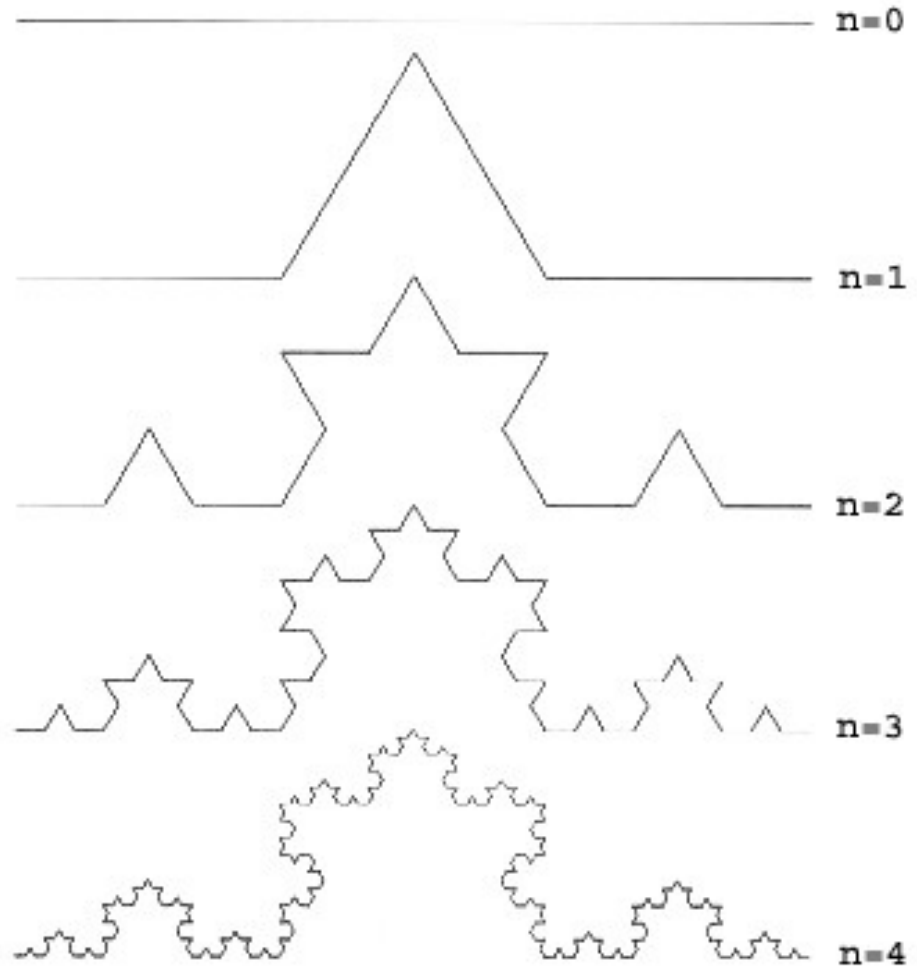
F

$F \rightarrow F+F--F+F$

$+ \rightarrow +$

$- \rightarrow -$

$\delta = 60^\circ$



# Growing Classical Fractals with L-Systems

- Space filling curves (Hilbert curve)
- Using additional symbols which are ignored by the turtle to control derivation

L-system:

Axiom:

Production rules:

Hilbert curve

L

$L \rightarrow +RF-LFL-FR+$

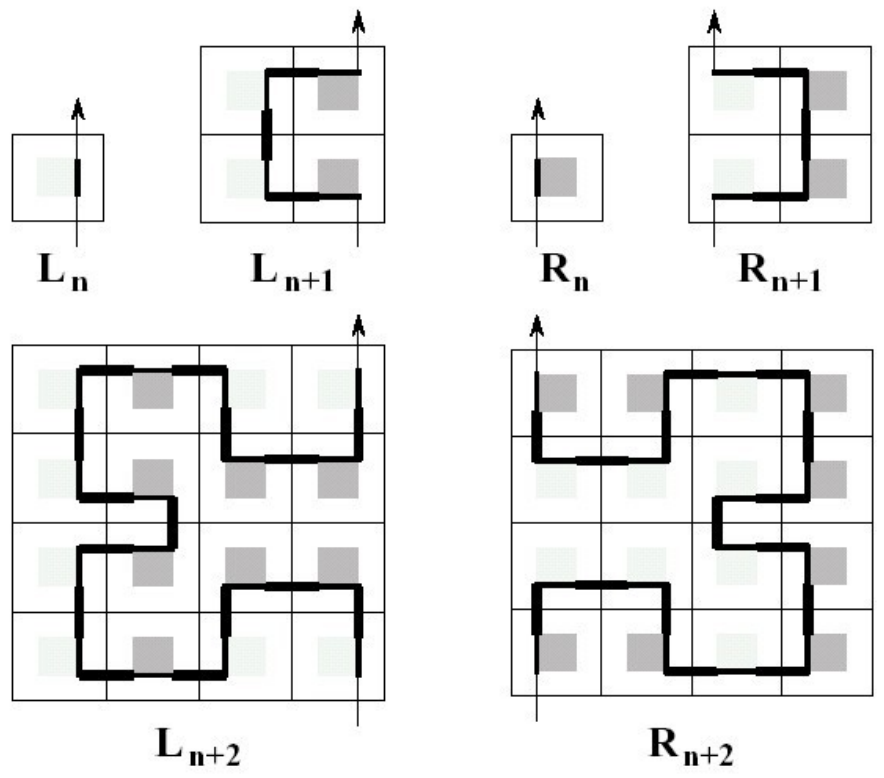
$R \rightarrow -LF+RFR+FL-$

$+ \rightarrow +$

$- \rightarrow -$

Parameter:

$\delta = 90^\circ$





# L-System Trees and Bushes

## Stacking of turtle states

[ save the current state of the turtle at the top of the stack

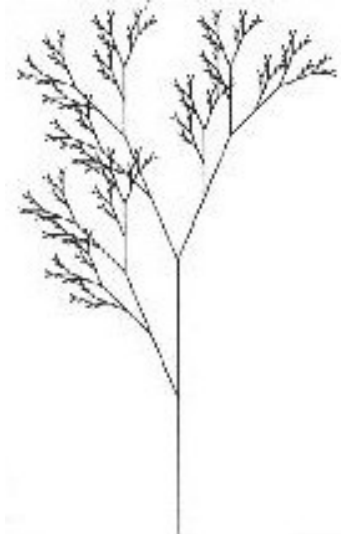
] pops the top state from the from the stack and put the turtle into this state



Axiom: F  
 Rules:  $F \rightarrow F[+F]F[-F]F$   
 Parameter:  $\delta = 25.7^\circ$



Axiom: F  
 Rules:  $F \rightarrow FF+[+F-F-F]-[-F+F+F]$   
 Parameter:  $\delta = 25^\circ$



Axiom: B  
 Rules:  $F \rightarrow FF$   
 $B \rightarrow F[+B]F[-B]+B$   
 Parameter:  $\delta = 20^\circ$

# Non Deterministic L-Systems

- At least one symbol has more than one production
- There must be a mechanism which selects one of the productions for each symbol during derivation
  - Stochastic L-systems
  - Context-sensitive L-systems
  - Parametric L-systems

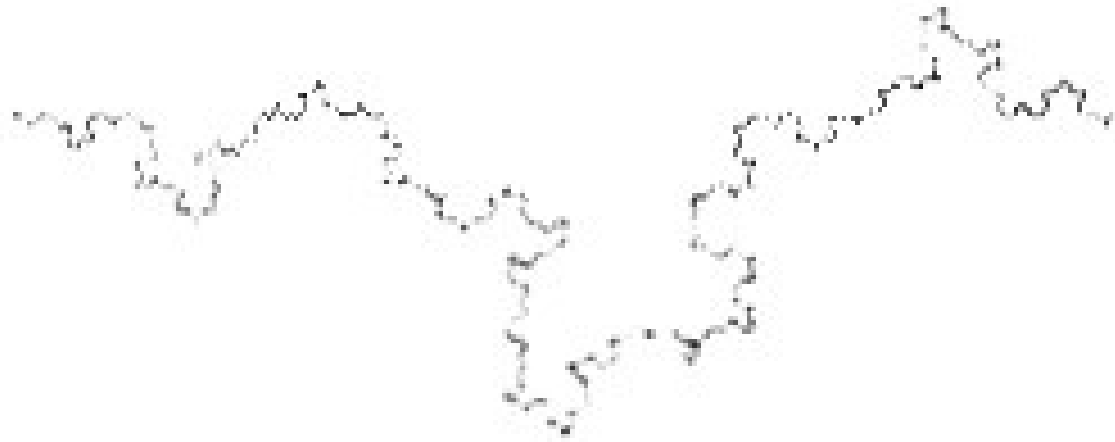
# Stochastic L-Systems

- Different productions for a symbol are selected randomly
- Used to generate variation among individuals

L-system: Stochastic Weedlike Plant  
Axiom: F  
Rules: F  $\rightarrow$  F[+F]F[-F]F (probability 1/3)  
F  $\rightarrow$  F[+F]F (probability 1/3)  
F  $\rightarrow$  F[-F]F (probability 1/3)  
Parameter:  $\delta = 25.7^\circ$



# Stochastic L-Systems



L-system: Random Koch Curve

Axiom: F

Rules:  $F \rightarrow F-F++F-F$  (probability 1/2)

$F \rightarrow F--F+F$  (probability 1/2)

Parameter:  $\delta = 60^\circ$

# Context-sensitive L-Systems

- The selection of a production for a symbol depends on the adjacent symbols in the current string

$$- lc < A > rc \rightarrow B$$

- 1L-systems, 2L-systems, IL-systems

$\omega$ : baaaaaaaa

$p_1$ : **b** < a  $\rightarrow$  b

$p_2$ :     b  $\rightarrow$  a

baaaaaaaa

abaaaaaaaa

aabaaaaaaaa

aaabaaaaaa

aaaabaaaaa

...

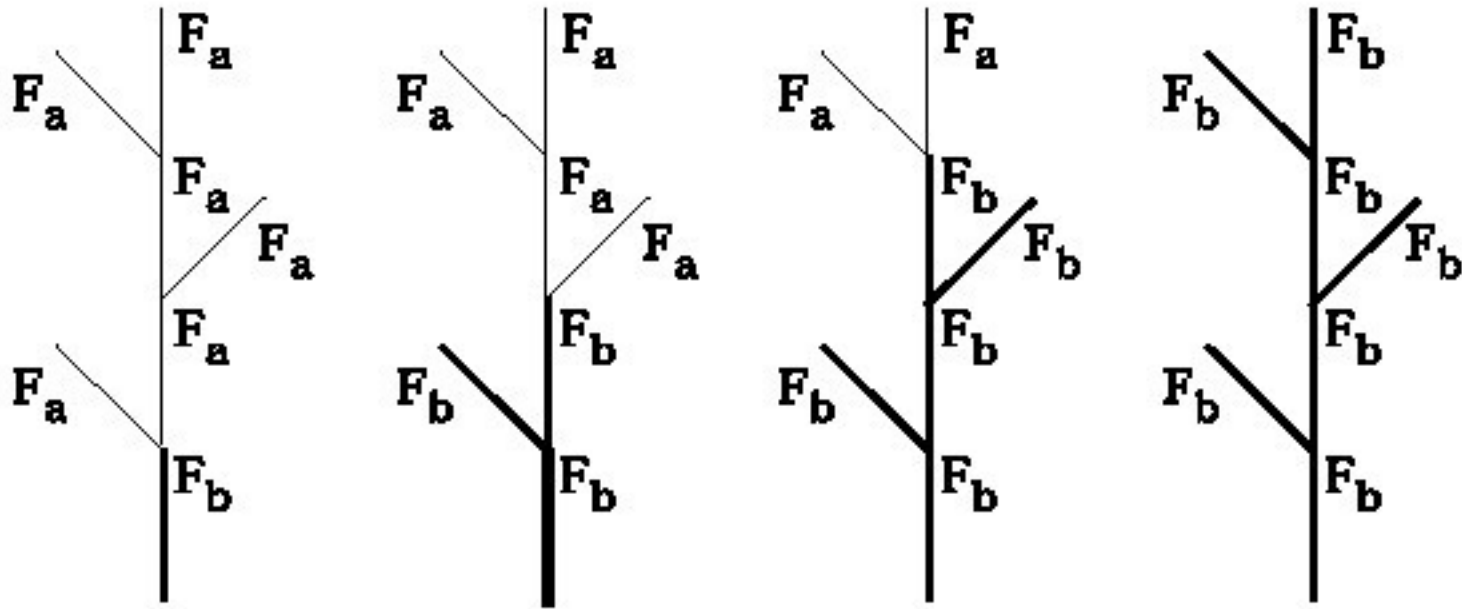
**xy** < a > **cde**  $\rightarrow$  aaa

zaxyacdef

zaxyaaa**cdef**

# Context-sensitive L-Systems

- To simulate the propagation of signals (hormones, nutrients) between parts of a plant



#ignore: + -

$\omega$ :  $F_b[+F_a]F_a[-F_a]F_a[+F_a]F_a$

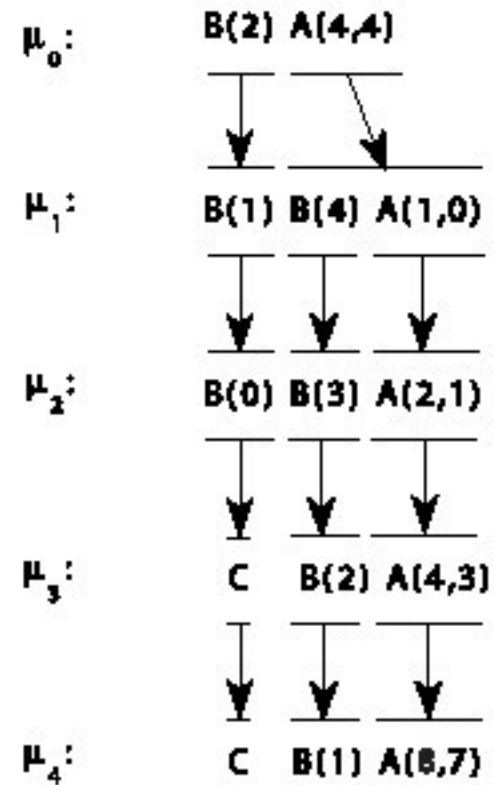
$p$ :  $F_b < F_a \rightarrow F_b$

# Parametric L-Systems

- Symbols are associated with a finite set of parameters
- Parameter values are used to select productions and to control turtle geometry
  - $id : lc < pred > rc : cond \rightarrow succ : prob$
- Important for plant modeling, because the geometry of a plant is the result of its developmental process

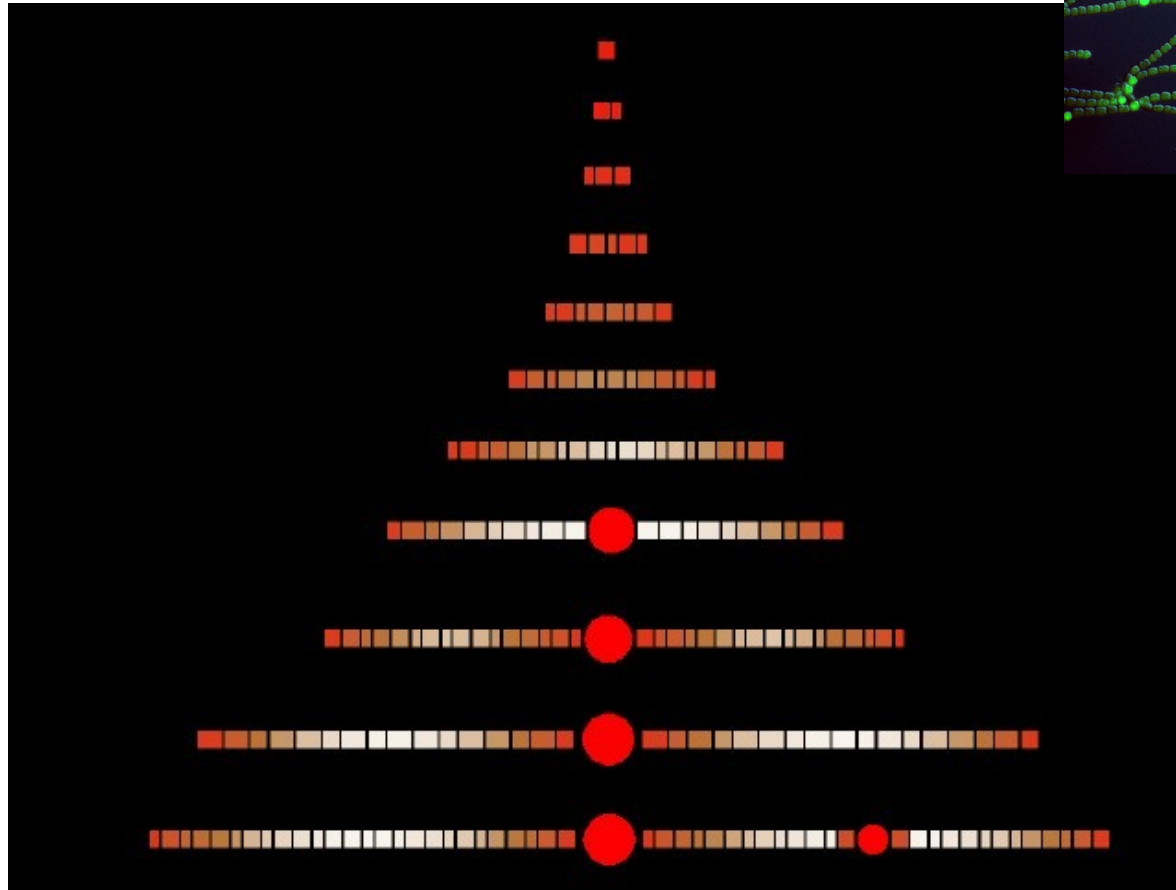
# Parametric L-Systems

$\omega : B(2)A(4, 4)$   
 $p_1 : A(x, y) : y \leq 3 \rightarrow A(x * 2, x + y)$   
 $p_2 : A(x, y) : y > 3 \rightarrow B(x)A(x/y, 0)$   
 $p_3 : B(x) : x < 1 \rightarrow C$   
 $p_4 : B(x) : x \geq 1 \rightarrow B(x - 1)$



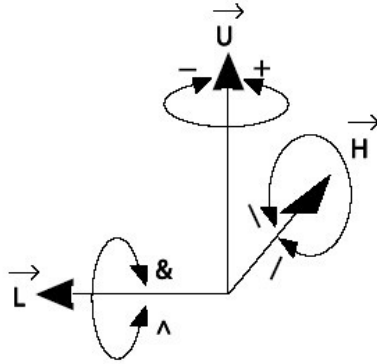


# Parametric L-Systems



Development of a filament (*Anabaena catenula*)

# 3D Graphics Representation



Turtle orientation in space

$\vec{H}$  the turtle's heading  
 $\vec{L}$  the direction to the left  
 $\vec{U}$  the direction up

rotation of the turtle:  $[\vec{H}' \vec{L}' \vec{U}'] = [\vec{H} \vec{L} \vec{U}] \mathbf{R}$   
 $\mathbf{R}$  rotation matrix

+ turn left by angle  $\delta$ , using  $\mathbf{R}_U(\delta)$

- turn right by angle  $\delta$ , using  $\mathbf{R}_U(-\delta)$

& pitch down by angle  $\delta$ , using  $\mathbf{R}_L(\delta)$

^ pitch up by angle  $\delta$ , using  $\mathbf{R}_L(-\delta)$

\ roll left by angle  $\delta$ , using  $\mathbf{R}_H(\delta)$

/ roll right by angle  $\delta$ , using  $\mathbf{R}_H(-\delta)$

| turn around, using  $\mathbf{R}_U(180^\circ)$

$$\mathbf{R}_U(\alpha) = \begin{bmatrix} \cos \alpha & \sin \alpha & 0 \\ -\sin \alpha & \cos \alpha & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\mathbf{R}_L(\alpha) = \begin{bmatrix} \cos \alpha & 0 & -\sin \alpha \\ 0 & 1 & 0 \\ \sin \alpha & 0 & \cos \alpha \end{bmatrix}$$

$$\mathbf{R}_H(\alpha) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos \alpha & -\sin \alpha \\ 0 & \sin \alpha & \cos \alpha \end{bmatrix}$$

# 3D Graphics Representation



$n=7, \delta=22,5^\circ$

$\omega: A$

$p_1: A \rightarrow [ \&FL!A ] // // // [ \&FL!A ] // // // [ \&FL!A ]$

$p_2: F \rightarrow S // // // F$

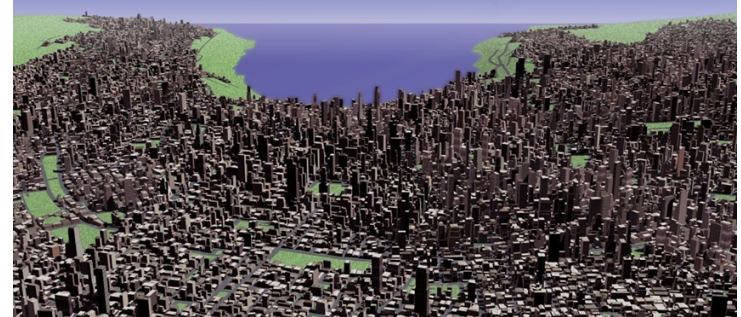
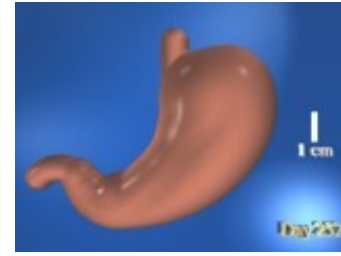
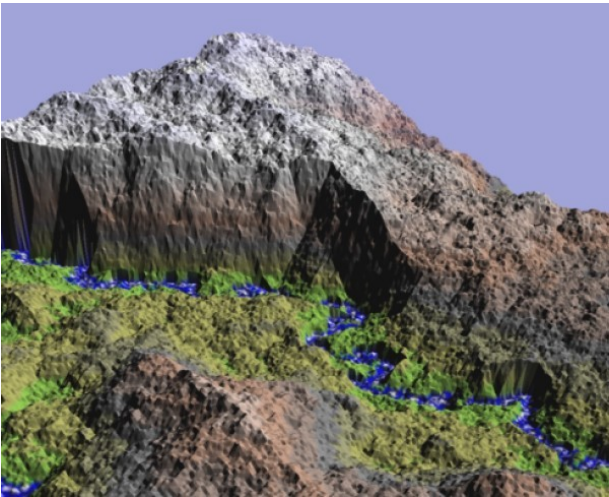
$p_3: S \rightarrow FL$

$p_4: L \rightarrow [ \text{''}^{\wedge\wedge} \{ -f+f+f- | -f+f+f \} ]$

# Application of L-Systems

- Simple multicellular organisms
- Plants, development of plants
- Rivers
- Seashells
- City models (street maps, buildings)
- Development of human organs
- Classical fractal forms
- Generating of music (3D L-systems as MIDI files)

# Application of L-Systems



# References

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