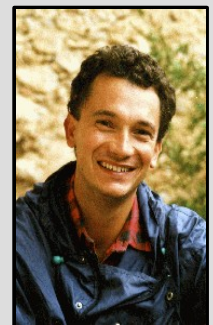


Efficient implementation of entropy estimation for registration

Mobility project report
5.12.2005 - 26.3.2006

Project information

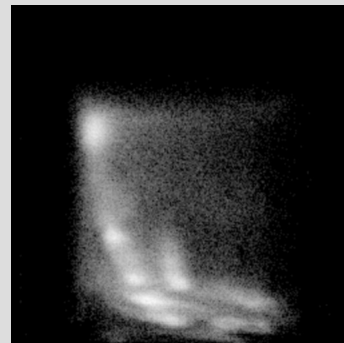
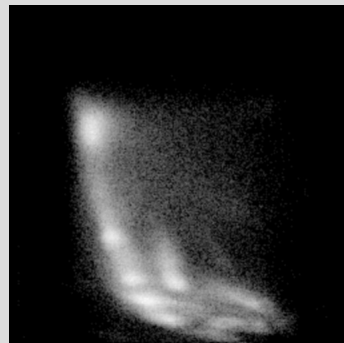
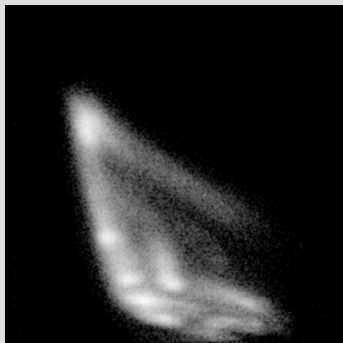
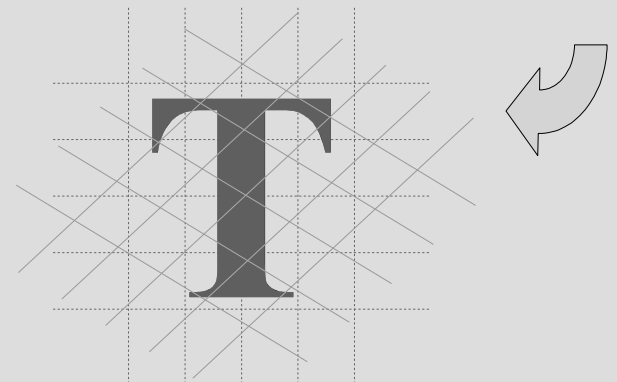
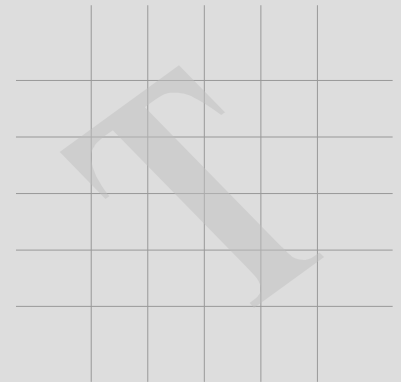
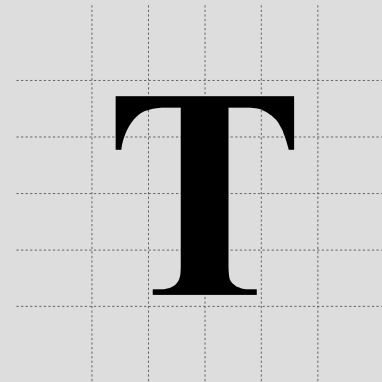
- Creative vision in practice
- Partners:
 - Neovision
 - Center for Machine Perception, Czech Technical University
 - part of the Miracle Center of Excellence



Leonardo Da Vinci mobility, 5.12.2005–26.3.2006
13 weeks

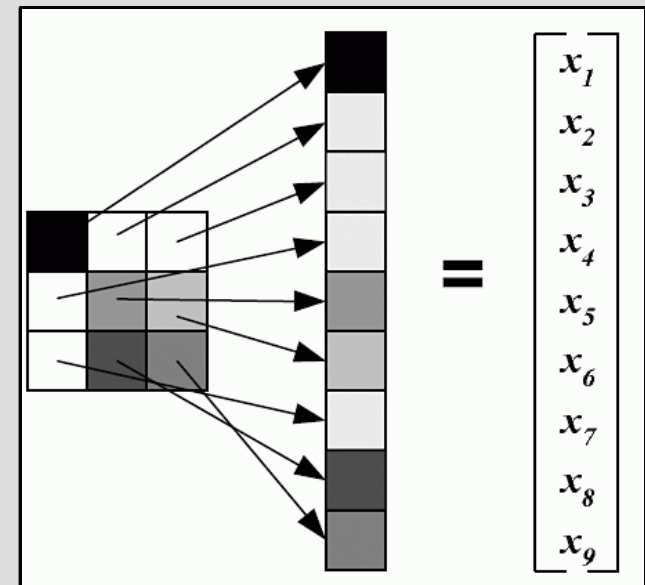
Registration using MI

- Spatial alignment of images
- For transformation evaluation
 - => similarity measure
- Geometrical features
- Corresponding voxel values
 - SSD, correlation
 - Dispersion of joint histogram
 - => joint entropy, MI



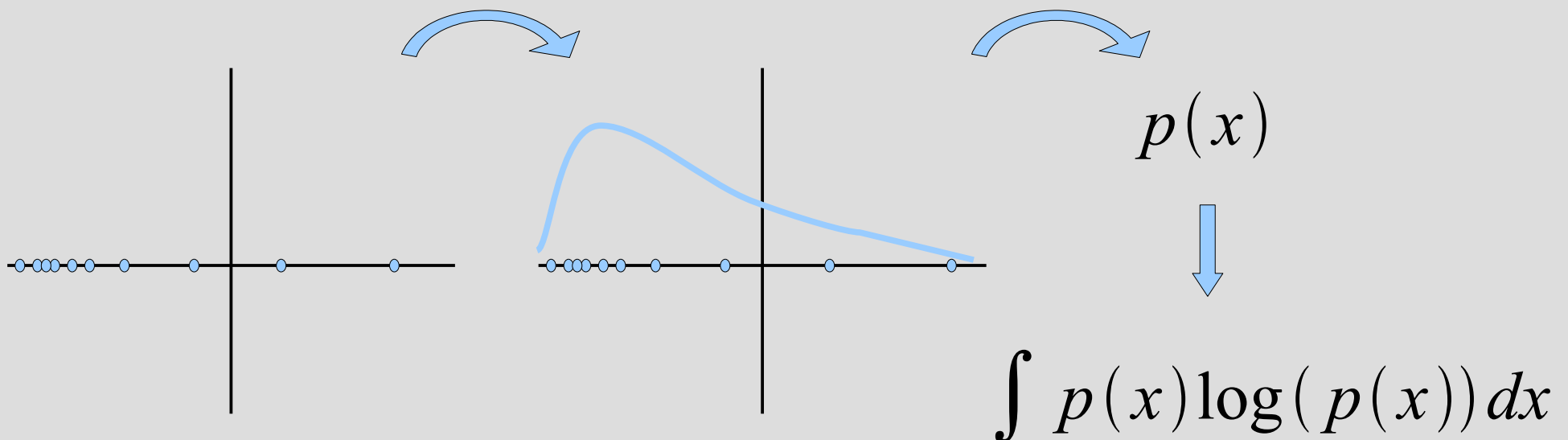
Problem introduction

- Mutual information criterion for image registration => estimation from finite sample
 - $10^5 - 10^7$ data points => fast, if we want to use the whole sample => not Parzen windows
 - High dimensional features (color, spatial neighborhood) to use more information => reliable for high dimensional distributions => no histogram based estimation
- Used as an optimization criterion => statistically stable



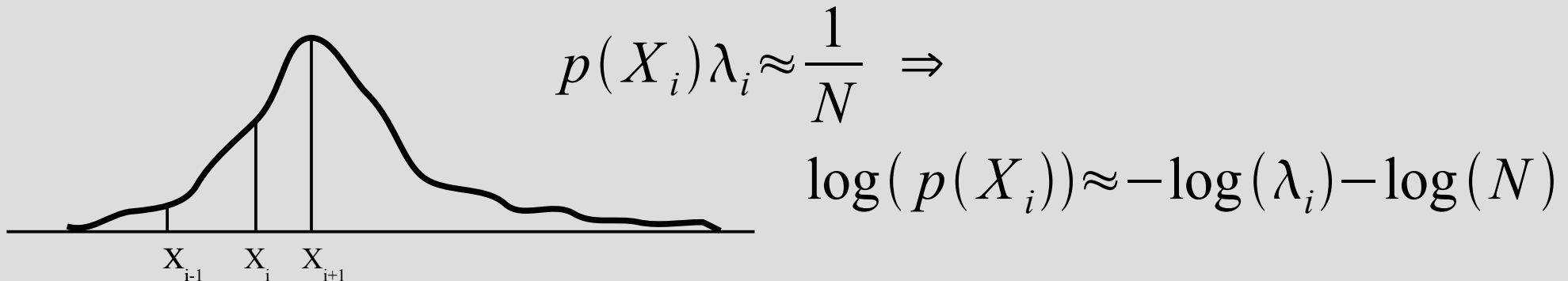
Estimating entropy

- Plug-in estimates
 - estimate of the distribution, which is plugged into the definition of entropy
 - histogram estimate, mixture of Gaussians, Parzen windows



Estimating entropy

- Order statistics and nearest neighbor estimates
 - estimates from the distances between neighbor values in the sample
 - for 1D order statistics
 - for arbitrary D nearest neighbor
 - In 1D case
 - Expectation of probability mass between two successive points in order statistics is constant



Estimating entropy

- Compression estimates
 - entropy is the lower bound on the size of lossless compressed data
 - Lempel-Ziv
 - Burrows-Wheeler
 - compressing the data \Rightarrow size after is the upper bound on entropy
 - the better compression the better estimate

Implemented approach

- modified Kozachenko – Leonenko nearest neighbor estimate
- Based on an unpublished work of Jan Kybic
- kD tree used as underlying data structure for all-NN search
- for the use in optimisation procedures an update operation designed
- for the search a Best Bin First approach used

Properties of KL Estimator

- Kozachenko – Leonenko nearest neighbor estimator [KoLe]

$$KL(\{X_1, \dots, X_N\}) = -\frac{1}{N} \sum_{j=1}^N [\log(\lambda_j) + \log[2(N-1)] + \frac{\gamma}{\ln(2)}]$$

- Modified for L_∞ norm and dimensionality d

$$KL(\{X_1, \dots, X_N\}) = -\frac{1}{N} \sum_{j=1}^N [d \log(\lambda_j) + \log[2^d(N-1)] + \gamma]$$

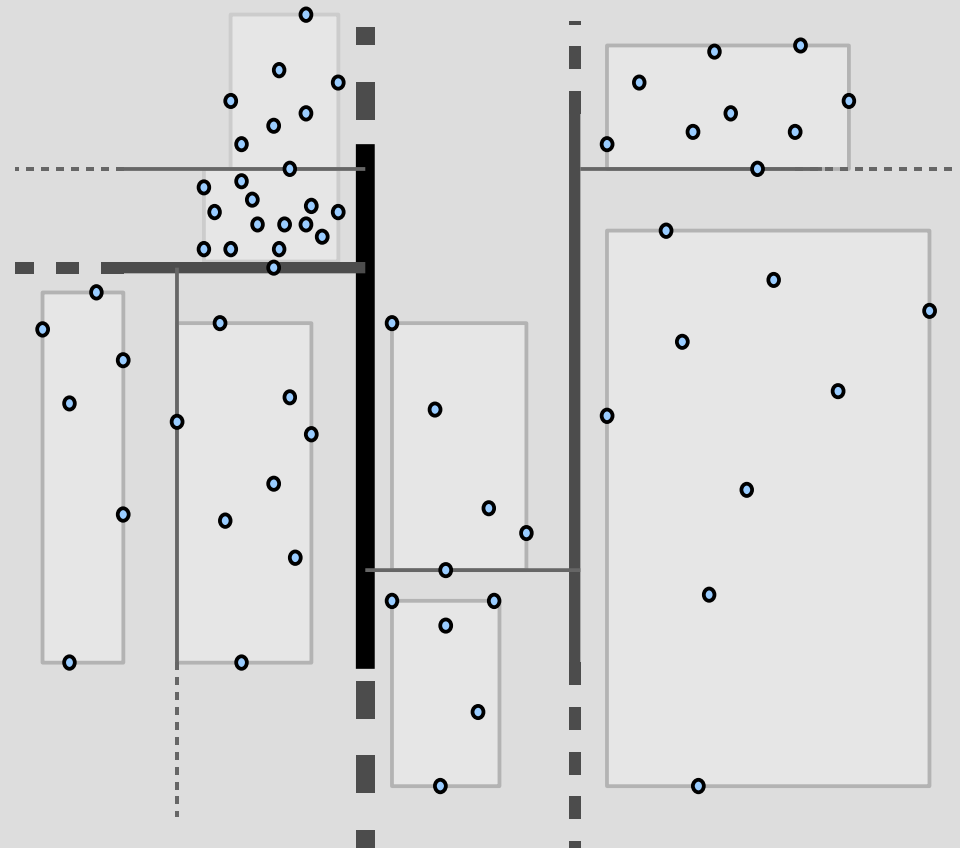
- Based directly on sample values
- Asymptotically unbiased
- Binless \Rightarrow no „curse of dimensionality“
- Mean square consistent $\Rightarrow \lim_{n \rightarrow \infty} E[(H_n - H(X))^2] = 0$

Efficient implementation issues

- All nearest neighbor search
 - $O(dN^2)$ for brute force approach
 - More efficient
 - Space partitioning trees – kD trees, box-decomposition trees
 - Voronoi diagrams
 - Approximate nearest neighbor
- Quantization
 - Multiple points
 - KL estimator is based on continuous distribution assumption

kD tree

- Binary space decomposition tree
- Root node represents the whole space
- Children => cutting the parent hyperrectangle by a plane
=> loose bounding box for each node
- Tight bounding boxes maintained
- Axis aligned hyperrectangles
=> L_2 norm used
- Optional parameter - number of points in leaf



Quantization problem

- KL Estimator derived with continuous impulse-free distribution assumption
- Quantization \Rightarrow equal values in sample \Rightarrow

$$\log(\lambda_i) = \log(0) = -\infty$$

- Used solution

$$\log(\lambda_i) \Rightarrow \log\left(\frac{\epsilon^d}{k_i}\right) \text{ for } \lambda_i < \epsilon$$

Implementation details

- In ANSI C++
- Inspired by previous Ocaml implementation, but written from scratch
- Platform independent
- Successfully compiled on Win32 platform with GCC compiler in MinGW environment and MS Visual C++ compiler
- Working environment: msys, mingw, Code::Blocks



Experiments – artificial data

- Run on Celeron 2 Ghz, 248 MB RAM
- Entropy estimation for 1 000 000 normally distributed points, for leaf size 40, max visit 1000, for $d=1$ 100

Dimensionality	True entropy	Building time	Iterating time	Entropy error
1	1.41894	5,437	1,563	-0.000538472
3	4.25682	8,937	16,641	-0.00378593
5	7.09469	10,609	119.547	-0.0115131
10	14.1894	13.578	654.015	1.20752

Experiments – artificial data

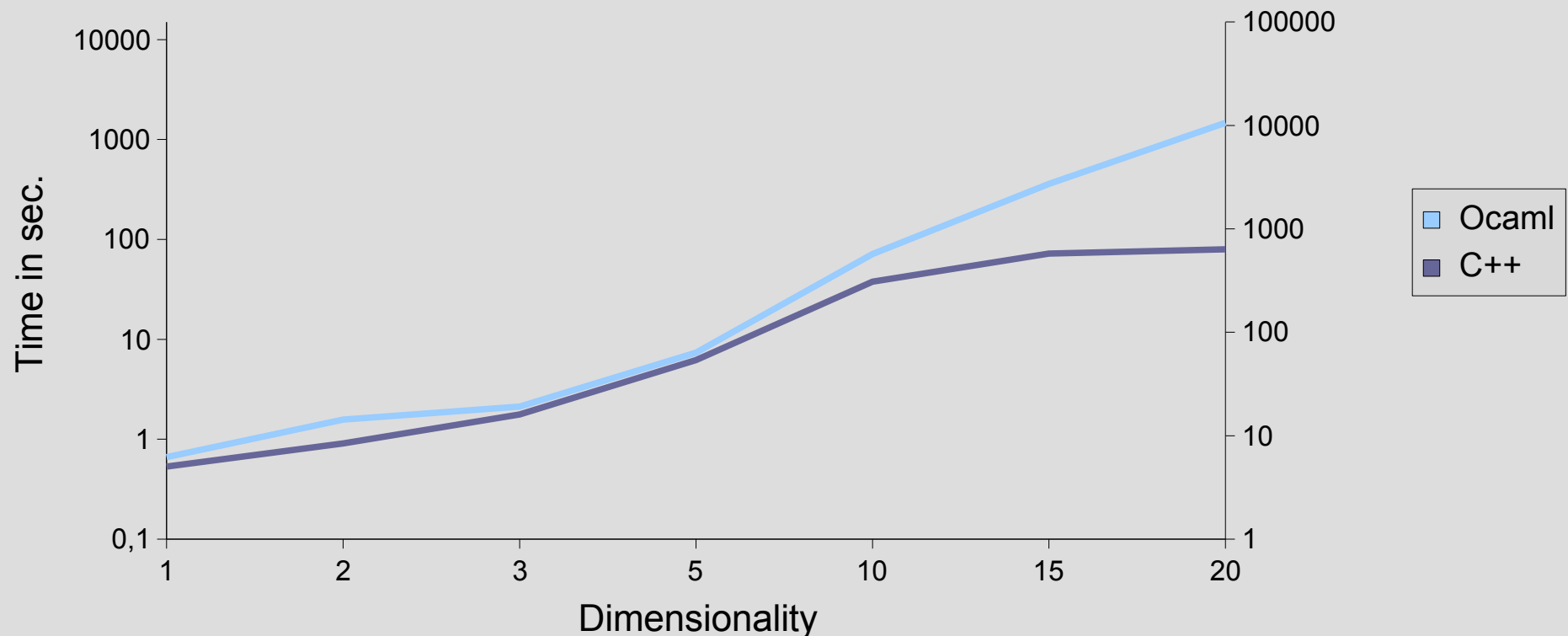
- Run on Celeron 2 Ghz, 248 MB RAM
- Entropy estimation for 100 000 3D normally distributed points, with quantization

Step	Building time	Iterating time	Entropy error
0	0,5500	1,3203	-0,001134730
0,00001	0,5576	1,3206	-0,000190042
0,0001	0,5612	1,3188	-0,004629920
0,001	0,5532	1,3158	-0,005963390
0,01	0,5500	1,1516	-0,036931000
0,1	0,5188	0,3140	-8,399770000
1	0,2564	0,0108	-19,362000000

Experiments – artificial data

- Run on Pentium IV 2 GHz and Celeron 2GHz

Comparison of all - NN iteration for Ocaml and C++ implementations
100 000 uniformly distributed points, leaf size 40
C++ times in scale 1/10, Both in logarithm scale



Open problems and future work

- Quantization
 - Low amplitude noise
 - Smoothing
 - Derivation of estimator with the quantization noise assumption
- Derivation estimation
- Mutual information estimation
 - $H(X) + H(Y) - H(X, Y)$
 - Direct nearest neighbor MI estimator [Kraskov] implementation in this framework
- Normalized MI experiments $\frac{H(X) + H(Y)}{H(X, Y)}$

References

- [KoLe] Kozachenko L., Leonenko N., „On statistical estimation of entropy of random vector“, Problems Infor. Transmiss., 23(2):95–101, 1987
- [NumRec] Numerical recepies in C,
<http://www.library.cornell.edu/nr/bookcpdf.html>
- [Kraskov] Kraskov A., Stogbauer H., Grassberger P., "Estimating Mutual Information", ArXiv cond-mat/0305641, 2003